SAFETY NOTE

- This appliance can be used by children aged from 8 years and above and persons with reduced physical, sensory or mental capabilities or lack of experience sensory or mental capabilities or lack of experience and knowledge if they have been given supervision or instruction concerning use of the appliance in a safe way and understand the hazards involved. C. Children shall not play with the appliance. 3. Cleaning and user maintenance shall not be made by children without supervision. 4. If the supply cord is damaged, it must be replaced by the manufacturer its service agent or similarly qualifier.

- the manufacturer, its service agent or similarly qualified persons in order to avoid a hazard.

 5. WARNING: the drive shall be disconnected from its power source during cleaning, maintenance and when
- power source during oceaning, maintenance and when replacing parts.

 6. The instructions shall state that the A-weighted emis sion sound pressure level of the drive is equal to or less than 70 dB(A), e.g. by writing LpA ≤ 70 dB(A).

 7. The mass and the dimension of the driven part shall be compatible with the rated torque and rated operating time.
- 8. The type of driven part the drive is intended for.
- WARNING: Important safety instructions. It is important for the safety of persons to follow these instructions.
 Save these instructions.
- 10. Do not allow children to play with fixed controls. Keep remote controls away from children.

 11. Frequently examine the installation for imbalance and
- 11. Flequently examine the installation to inflatance and signs of wear or damage to cables and springs. Do not use if repair or adjustment is necessary.

 12. Watch the moving shutter and keep people away until the shutter is completely closed.

 13. WARNING: Important safety instructions. Follow all
- instructions, since incorrect installation can lead to severe injury.

 14. Before installing the drive, remove any unnecessary
- cords and disable any equipment not needed for powered operation.



DM35(45)F/SW, DM45E/SW

Instruction | A-04







| Norking Temperature: -10°C ~ +65°C | Radio Frequency: 433.925MHz |
|---|------------------------------------|
| Rated Voltage: AC 120V,60Hz; AC 220V,60Hz; AC 230V,50Hz | Thermal Protection Time: 4 minutes |















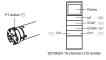






Important Safety Instructions To Be Read Prior To Operation.

Setting Notice



Essential Settings
Step 1 to 3 must be con



 $\text{Pl} \rightarrow \blacksquare$

Press P1 button for 2S (1 jog), release button and long beep once, within 10S, press STOP for 2S (2 jogs and 3 beeps), the motor has been paired successfully.



UP DOWN

Press and hold UP and DOWN buttons simultaneously for 2S (1 jog), the direction has been switched successfully.

3 Setting Upper and Lower Limits

UP UP STOP

Press UP for 2S, operate the motor to desired upper limit position, press and hold UP and STOP buttons simultaneously for 2S (2 jogs and 3 beeps), upper limit is set.

DOWN DOWN STOP Press DOWN for 25 operate the motor to desired lower limit position, priess and hold DOWN and STOP buttons simultaneously for 25 (2) logs and 3 beeps), lower limit is set.

* Its freely to set the upper limit or lower limit firstly; In the no-limit state, the motor jog runs; Press and hold UP or DOWN for 2S to run continuously, after the limit is set, the motor runs continuously.

4 Add A Preferred Position

5 Adjust Limits

Press and hold UP and STOP buttons simultaneously for 5S (1 jog and 1 long beep), operate the product to desired new upper limit position, press and hold UP and STOP buttons simultaneously for 2S (2 jogs and 3 beeps), the new upper limit is coronamed accessfully.

Press and hold DOWN and STOP buttons simultaneously for 58 (1 jog and 1 long beep), operate the product to desired new lower limit position, press and hold DOWN and STOP buttons simultaneously for 28 (2 jog and 3 beep), here here lever limit a long-gramment successible.

"This operation should be certified on when there is a limit. Enter Tim Mode for 2 minutes if not confirm the new level, present used to the long mode and restor the noting limit in position.

6 Activate / Deactivate Jog / Tilt Mode

^+ V → = UP DOWN STOP

Press and hold UP and DOWN buttons simultaneously for 5S (1 log), press STOP (1 log and 1 long beep), log / tilt mode is activated. If motor jogs twice and beeps 3 times, log / tilt mode is deadtivated.

* Press UP or DOWN for more than 25, the motor confinues run; It must be done after setting the upper limit and the lower limit; Close the jog & tilt function, the motor running continuously.

7 Pair / Unpair Additional Emitter

 $\left(\stackrel{P2}{\bigcirc} \right)_{\bullet} \rightarrow \left(\stackrel{P2}{\bigcirc} \right)_{\bullet} \rightarrow \left(\stackrel{P2}{\bigcirc} \right)_{\bullet}$ P2(a) P2(a) P2(b)

Press P2 (1 jog and 1 beep) and P2 (1 jog and 1 beep) on existing emitter, press P2 on new emitter to add (2 jogs and 3 beeps), new emitter is paired to the motor.

• Repeat same procedure will unpair additional emitter.

Method two

Prices P2 (1) log and 1 beep) and P2 (1) log and 1 beep) on existing entitler, prices STOP on new entitler for 25 to add (2) logs and 3 beeps), new entitler is paired to the motor.

(P1) → (B)
P1 STOP(b)

Press P1 button for 2S (1 jog), release button and long beep once, press STOP on new emitter for 2S to add (2 jogs and 3 beeps), new emitter is paired to the motor.

8 Delete All Emitters

P2 STOP P2

Press P2 (1 jog and 1 beep), press STOP (1 jog and 1 beep) and press P2 (2 jogs and 3 beeps), all emitters are deleted.

9 Cancel All Limits

 $\left. \begin{array}{c} P2 \\ \end{array} \right. \rightarrow \left. \begin{array}{c} P2 \\ \end{array} \right)$ P2 DOWN P2

Press P2 (1 jog and 1 beep), press DOWN (1 jog and 1 beep), and press P2 (2 jogs and 3 beeps), all limits are canceled.

10 Smartphone Control















* Please scan below QR code to learn more about link up DM35(45)F/SW or DM45E/SW with his setup Connector APP, and establish connection with other IoT applications.





Quick Index

| Ξ | | | | |
|----|---------------------------------------|---|--|--|
| Ξ | Settings | Steps | | |
| 1 | Pairing | P1 (hold down 2x) Stop (hold down 2x) | | |
| 2 | Switch Rotating Direction | Up + Down (hold down 2x) | | |
| | Setting Upper and Lower Limits | 1 Set upper limit | Up (hold down 2x) → Up + Stop (hold down 2x) | |
| 3 | | 2 Set lower limit | Down (hold down 2x) Down + Stop (hold down 2x) | |
| 4 | Add / Delete Preferred Position | P2 → Stop → Stop | | |
| | Adjust Limits | 1 Adjusting the upper limit position | Up + Stop (hold down Se) → Up or Down → Up + Stop (hold down 2x) | |
| 3 | | 2 Adjusting the lower limit position | Down + Stop (hold down Ss) → Up or Down → Down + Stop (hold down 2s) | |
| 6 | Activate / Deactivate Jog / Tilt Mode | Up + Down (hold down Ss) → Stop | | |
| Π | Pair / Delete Additional Emitter | 1 Pair / Delete Additional Emitter | P2(a) → P2 (a) → P2(b) | |
| 7 | | 2 Pair Additional Emitter | $P2(a) \to P2\left(a\right) \to Stop(b) \ (hold \ down \ 2a)$ | |
| | | 3 Pair Additional Emitter | P1 (hold down 2x) → Stop(b) (hold down 2x) | |
| 0 | Delete All Emitters | P2 → Stop → P2 | | |
| 9 | Cancel All Limits | P2 → Down → P2 | | |
| 10 | Smart APP Pairing | Press and hold P1 for about 2s until motor beep once, then tap "NEXT" button on the APP | | |
| | | Press P2 twice, then tap "NEXT" button on the APP | | |
| _ | | | | |

| bsues | Possible causes | Solution |
|---|---|---|
| | Power Failure Or Incorrect Connection | Double check power and cable connections, follow-wiring instructions. |
| The motor has no response | emitter battery is low capacity | Replace battery |
| | Radio interference / shielding | Check antenna on motor is intact and exposed. Check for possible source of radio interference. |
| | Out of radio control range | Try control within closer range |
| The emitter cann't control single motor | Multiple motors are paired to the same channel. | Always reserve an individual correctly (refer to motor functions) |
| | | Try to use multi-channel emitters to control multi-motor projects, ensure each channel to control one single motor |
| The motor doesn't run or starts too slowly or make loud noise | Connections are incorrect. | Check connections |
| | Incorrect installation or overload | Check installation or overload |
| The motor stops during the going up or going down | The motor has reached the lower limit | Adjust the new lower limit |
| | Running time exceeds 4 min | Let the motor cool down for about 20 minutes |